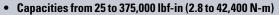
MCRT® 48800V & 49800V **ULTRA PRECISE SHAFT TORQUEMETERS**

Have Analog and Digital Outputs And The Highest Accuracy of **Any Similar Torque Sensor, Transducer or Torquemeter**



Output Torque, Speed & Power in Analog & Digital Form

- 400% Overload and 300% Overrange
- 0.0006% Temperature Performance
- 0.02% Combined Nonlinearity and Hysteresis
- 0.01% 48 Hour Drift
- Accredited, NIST Traceable* CW and CCW Cal
- **Bipolar Rotor Shunt Cal NIST Traceable***
- **Hardened to EMI From Adjustable Speed Drives**
 - ±5.000/±10.000V Analogs of Torque, Speed & Power
 - Engineering Unit Digital Outputs of Torque, Speed & Power
 - 1 kHz Bandwidth; 13 Constant Delay Signal Filters
 - Select from 33 Units of Measure Without Re-calibration
 - Shaft Power Calculated 7800 Times/Second
 - 128 µs Max/Min Data Acquisition
 - Plated Alloy Steel Shaft, Stainless Steel Housing

*NIST traceable calibration performed in our accredited laboratory (NVLAP Lab Code 200487-0). For details visit www.himmelstein.com or follow the accreditation link at www.nist.gov.



These strain gage Torquemeters measure and output *shaft* torque in analog and digital form. Option Z adds speed <u>and</u> shaft power. Their outstanding performance is due, in part, to industries highest Overrange which avoids clipping real-world torque peaks and torsionals. Without high Overrange, clipped peaks cause large errors; see AN 20805B.

Tight temperature compensation reduces drive heating and gradient effects. Also enhancing performance is elimination of pots subject to misadjustment under vibration and by unauthorized users. The Torquemeters are hardened against VFD and other noise sources. Bipolar rotor shunt cal verifies calibration of the entire data chain in CW and CCW modes. Included software displays, plots and stores real-time data on your PC. It also

Displays and Stores Max/Min and Spread Data. Choose RS232, RS422, RS485 or USB (option) communication. Input power is a single, unregulated voltage. Reverse polarity protection is provided. Password protection is supported.

Two Performance Grades are offered; Standard (Code N), and Enhanced (Code C). They are available with 200% (MCRT® 48800V Series) and 400% (MCRT® 49800V Series) overload ratings. Option Z adds conditioned speed and power outputs. All outputs are simultaneously available in both analog and digital form. Should the torque, speed* or rotor temperature exceed the Torquemeters ratings, a warning flag(s) is generated.

^{*} Option Z is required to generate a Speed flag.



Table 1

Common Specifications	200% Overload MCRT® 48800V Series	400% Overload MCRT® 49800V Series						
Torque and Speed (Option) Scaling	Factory Set @ Transducer Torque Capacity and Maxim	um Speed. Field Resettable to any lower value.						
Power (Option) Range – See Note 1	Scaling is Factory Set @ the Product of Full Scale Torque, Speed and a Constant. It is user re-settable							
Units of Measure	Default units are lbf-in and, if Option Z is specified, rpn specified or, user selected with a PC and furnished sol							
Torque – Combined Nonlinearity ² and Hysteresis ² (% of F.S.)	Code N (Standard Performance): ≤±0.04 Code C (Enhanced Performance): ≤±0.02	Code N (Standard Performance): ≤±0.04 Code C (Enhanced Performance): ≤±0.02						
Speed & Power (Option Z) — Combined Nonlinearity ² and Hysteresis ² (% of F.S.)	except ≤± 0.1 for 25 & 375,000 lbf-in ranges	except ≤±0.05 for 50 lbf-in range						
Nonrepeatability ² (% of F.S.)	Torque and Power: Code N $\leq \pm 0.02$, Code C $\leq \pm 0.01$: Spe	eed ≤±0.01						
Zero Drift (% of F.S./deg. F.)	Torque and Power: Code N \leq ±0.001, Code C \leq ±0.0006:	Speed: none						
Span Drift (% of Rdg./deg. F.)	Torque and Power: ≤±0.002; Speed: none							
48 Hour Drift (% of F.S.)	Code N: ≤±0.03, Code C ≤±0.02							
Temperature Ranges (deg. F.)	Compensated: +75 to 175; Usable: -25 to +185; Storage: -65 to +225							
Overrange, (% of F.S.)	MCRT® 48800V: 150, MCRT® 49800V: 300 except ±15V max. on the Analog Output of both gr							
Signal Filter Cutoff Frequency ⁴ , Analog and Digital Data	Field selectable from 0.1 to 1,000 Hz in thirteen 1-2-5 steps using furnished software. Torque, and Speed Filters are identical and their cutoff frequencies track. Units are set to 10 Hz (default) unless Purchase Order specifies another frequency.							
Analog Output Signals, Auto Scaled	Torque and when option Z is specified, Speed and Pow	and when option Z is specified, Speed and Power. All are simultaneously available.						
Full Scale Torque ³ and Power ³	CW = +10V, CCW = -10V or, CW = +5V, CCW = -5V; field	changeable (Default = ±10V)						
Full Scale Speed ³	+10V or +5V for CW and CCW directions; field changes	ble (Default = +10V)						
Resistive Load	10,000 ohms, Minimum							
Capacitive Load	0.05 uF, Maximum							
Output Noise (% rms of F.S.)	MCRT® 48800V & MCRT® 49800V Series <0.02%							
Minimum Resolution (% of F.S.)	0.003 for both Analog and Digital Data.							
Data Acquisition Time	Torque: 128 μs, Speed: >800 rpm ≤1.25 ms, <800 rpm: 1	000/rpm ms, Power: 128 μs.						
Duplex Serial Communications Port Selectable as RS232, RS422 or RS485	Outputs Torque, Speed and Power (option Z) with unitand null values, cal info, units of measure, etc. and tes							
BAUD Rate	115,200. Drivers are Short circuit (current limit) and ± 1	5kV ESD protected						
120 Ω Termination (RS422/485)	Software selectable.							
Maximum Cable Length	4,000 feet for RS422 and RS485, 50 feet for RS232							
Supply Voltage ⁵ and Power	10 to 26 VDC at 2.7 watt, nominal. (Series 700 Instrume	700 Instrument compatible.)						
Connector Pinouts	See Page 6 tabulation.							

- $\textbf{1.} \quad \text{Torque and Speed (option Z) scaling may be re-set at any value} \leq \text{Transducer Full Scale Ratings}.$
 - For example: If the set Torque range is 10,000 lbf-in, and the set Speed range is 5krpm then Power Range = 10,000* 5000/83025 = 793.34 HP = 10V analog output.
- $\textbf{2.} \quad \text{Assumes torque scale is set to the device torque rating}.$
- $\textbf{3.} \quad \textbf{CW torque causes the shaft to turn CW when viewed from its driven end. CCW torque causes the opposite rotation. Power polarity tracks torque.}$
- $\textbf{4.} \ \ \, \textbf{Torque signal bandwidth upper limit is 1,000 Hz determined by integral Bessel response filters}.$
- 5. Reverse polarity protected.
- 6. "deg. F." denotes "degree Fahrenheit".
- $\textbf{7.} \quad \textbf{Specifications are subject to change without notice}.$



Order No 🕨	MCRT® 49804V	(5-3)	N	F	Z
	Model Number	Range	Performance Code: N or C	Foot Mount: N if none, F if yes	Speed/Power Option: Z if yes, N if no
	An MCRT® 49804V (5	i-3)NFZ is a 5,	000 lbf-in Torquemeter with Standar	d Performance, 400% Overload, Foot M	ount and Speed/Power option.

Table 2

		Torque	Ratings		Speed	Sha	nft	Rota			
MCRT®	Capacity		200% Overload		Rating	Stiffr		Iner	Weight		
Model	[lbf-in]	[N-m]	[lbf-in]	[N-m]	[rpm]	[lbf-in/rad]	[N-m/rad]	[ozf-in s²] [kg-m²]		[lb]	[kg]
48801V(25-0) ²	25	2.82	50	5.65	0 to ±15,000	2,320	262	0.0147	0.000104	12.5	5.67
48801V(5-1)	50	5.65	100	11.3	0 to ±15,000	5,550	627	0.0147	0.000104	12.5	5.67
48801V(1-2)	100	11.3	200	22.6	0 to ±15,000	13,000	1,470	0.0148	0.000104	12.5	5.67
48801V(2-2)	200	22.6	400	45.2	0 to ±15,000	24,400	2,760	0.0149	0.000105	12.5	5.67
48802V(5-2)	500	56.5	1,000	113	0 to ±15,000	42,300	4,780	0.0168	0.000119	12.7	5.76
48802V(1-3)	1,000	113	2,000	226	0 to ±15,000	50,000	5,640	0.0170	0.000120	12.7	5.76
48803V(2-3)	2,000	226	4,000	452	0 to ±8,500	263,000	29,800	0.0900	0.000636	13.2	5.99
48804V(5-3)	5,000	565	10,000	1,130	0 to ±8,500	458,000	51,700	0.123	0.000873	15.8	7.17
48804V(1-4)	10,000	1,130	20,000	2,260	0 to ±8,500	620,000	70,100	0.128	0.000904	16.0	7.26
48806V(2-4)	20,000	2,260	40,000	4,520	0 to ±8,000	2,710,000	306,000	1.387	0.00979	70.7	32.1
48806V(4-4)	40,000	4,520	80,000	9,040	0 to ±8,000	3,800,000	430,000	1.417	0.00100	71.3	32.3
48807V(5-4)	50,000	5,650	100,000	11,300	0 to ±6,000	5,960,000	674,000	2.401	0.00170	81.7	37.1
48807V(1-5)	100,000	11,300	200,000	22,600	0 to ±6,000	7,320,000	827,000	2.462	0.00174	82.5	37.4
48808V(2-5)	200,000	22,600	400,000	45,200	0 to ±3,600	27,500,000	3,110,000	12.61	0.00890	170.4	77.3
48808V(375-3) ²	375,000	42,400	750,000	84,700	0 to ±3,600	31,500,000	3,560,000	12.96	0.09150	172.2	78.1

^{1.} Stiffness is conservatively rated and includes the torsion section and shaft-ends.

Table 3

		Torque	Ratings		Speed	Sha	ıft	Rota			
MCRT®	Capa	city	400% Overload		Rating	Stiffn	iess ¹	Iner	Weight		
Model	[lbf-in]	[N-m]	[lbf-in]	[N-m]	[rpm]	[lbf-in/rad]	[N-m/rad]	[ozf-in s²]	[kg-m²]	[lb]	[kg]
49801V(5-1)	50	5.65	200	22.6	0 to ±15,000	13,000	1,470	0.0148	0.000104	12.5	5.67
49801V(1-2)	100	11.3	400	45.2	0 to ±15,000	24,400	2,760	0.0149	0.000105	12.5	5.67
49802V(25-1)	250	28.2	1,000	113	0 to ±15,000	42,300	4,780	0.0168	0.000119	12.7	5.76
49802V(5-2)	500	56.5	2,000	226	0 to ±15,000	50,000	5,640	0.0170	0.000120	12.7	5.76
49803V(1-3)	1,000	113	4,000	452	0 to ±10,000	263,000	29,800	0.0900	0.000636	13.2	5.99
49804V(25-2)	2,500	282	10,000	1,130	0 to ±10,000	458,000	51,700	0.123	0.000873	15.8	7.17
49804V(5-3)	5,000	565	20,000	2,260	0 to ±10,000	620,000	70,100	0.128	0.000904	16.0	7.26
49806V(1-4)	10,000	1,130	40,000	4,520	0 to ±8,000	2,710,000	306,000	1.387	0.00979	70.7	32.1
49806V(2-4)	20,000	2,260	80,000	9,040	0 to ±8,000	3,800,000	430,000	1.417	0.00100	71.3	32.3
49807V(25-3)	25,000	2,820	100,000	11,300	0 to ±6,000	5,960,000	674,000	2.401	0.00170	81.7	37.1
49807V(5-4)	50,000	5,650	200,000	22,600	0 to ±6,000	7,320,000	827,000	2.462	0.00174	82.5	37.4
49808V(1-5)	100,000	11,300	400,000	45,200	0 to ±3,600	27,500,000	3,110,000	12.61	0.00890	170.4	77.3
49808V(190-3)	190,000	21,500	750,000	84,700	0 to ±3,600	31,500,000	3,560,000	12.96	0.09150	172.2	78.1

^{1.} Stiffness is conservatively rated and includes the torsion section and shaft-ends.

^{2.} Enhanced Performance is not available on this model.



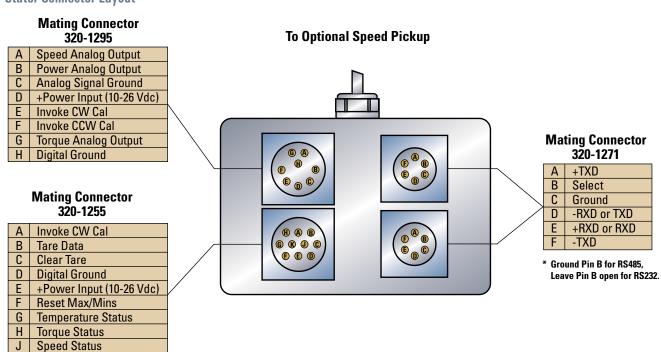
Table 4. Supported Units of Measure

Supported Units of Measure									
Torque	lbf-in, (default), lbf-ft, ozf-in, ozf-ft, N-m, kN-m, N-cm, kgf-m, kgf-cm, gf-cm								
Speed	rpm (default), rps, rph, rad/s, rad/min, rad/h, degree/min, degree/s, degree/h, grad/s								
Power	hp (default), hp (metric), kW, W, ft-lbf/min, ft-lbf/s, Btu/h, Btu/min, Btu/s, ton, cal/h, cal/min, cal/s								

Table 5. Cables

Available Cables	Cable lengths (XX) are 20, 50 and 100 feet. RS232 cables are limited to 50 feet. When purchased without cables, mating connectors are supplied at no added cost.
Torquemeter to Model 703 P/N 224-8722-XX	Powers Torquemeter, displays Torque, Implements Model 703 functions including Remote Cal, Tare, Analog Output, Zero, etc.
Torquemeter to Model 733 P/N 224-8800-XX	Powers Torquemeter, displays Torque and Speed, Implements Model 733 functions including Remote Cal, Tare, Power Calculation, Analog Output, Zero, etc.
Torquemeter to RS422/485 Host P/N 224-8360-XX	Connects Torquemeter to host computer and implements all Torquemeter functions. Requires external power input (10-26 Vdc). It is unterminated at host end.
RS485 Torquemeter to Torquemeter P/N 224-8361-XX	Provides Torquemeter interconnect when using RS485 protocol to read and control multiple Torquemeters with a single host computer.
Torquemeter to RS232 PC Port P/N 224-8359-XX	Connects Torquemeter to RS232 host Port. Implements all Torquemeter functions. 50 feet maximum. Use RS422/485 connection in noisy environments or for long runs.

Stator Connector Layout



Invoke CCW Cal



Outline Dimensions

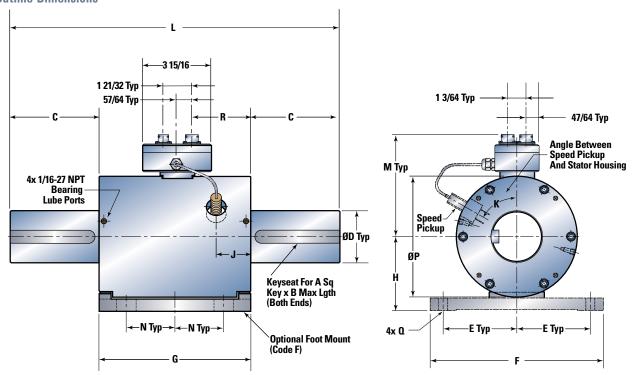


Table 6. Outline Dimensions [inch]

MCRT®		Outline Dimensions [inch]													
Model	A	В	C	D¹	E	F	G	Н	L	M	N	P	K	Q	R
48/9801V	0.187	1.125	1.50	0.625	2.250	5.50	5.50	2.250	8.50	3 55/64	1.50	3 15/32	90°	0.406	17/64
48/9802V	0.187	1.625	2.00	0.750	2.250	5.50	5.50	2.250	9.50	4 1/8	1.50	3 15/32	90°	0.406	17/64
48/9803V	0.250	1.719	2.22	1.000	2.625	6.25	5.65	2.500	10.00	43/32	1.50	3 31/32	60°	0.406	1 29/32
48/9804V	0.375	2.750	3.59	1.500	2.625	6.25	5.65	2.500	12.75	4 3/32	1.50	3 31/32	60°	0.406	1 29/32
48/9806V	0.625	3.500	4.13	2.500	4.250	10.00	8.75	4.250	17.00	5 5/8	2.81	6 15/16	60°	Note 2	2 23/64
48/9807V	0.750	4.500	5.13	3.000	4.250	10.00	8.75	4.250	19.00	5 7/8	2.81	6 15/16	60°	Note 2	2 23/64
48/9808V	1.000	6.500	7.56	4.500	4.250	10.00	8.50	5.000	23.03	6 19/64	2.81	8 3/16	60°	Note 2	2 1/64

^{1.} Tolerance of D diameter is +0.0000/-0.0005 for D <= 2.5'' and +0.000/-0.001" for D > 2.5''.

Table 7. Outline Dimensions [mm]

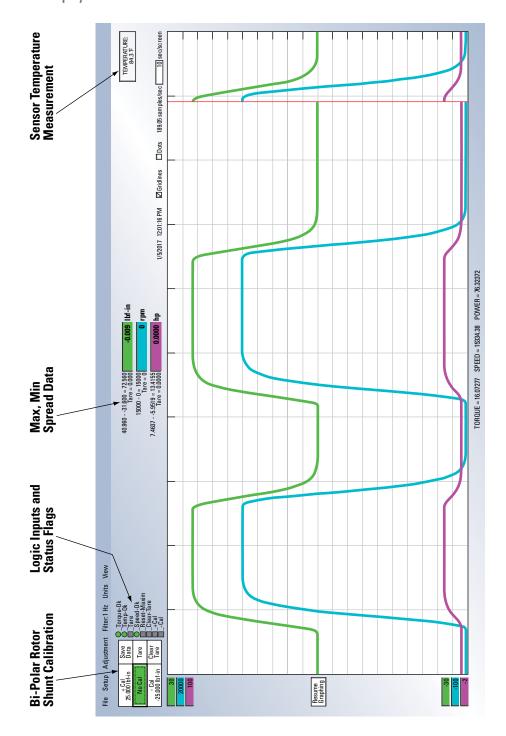
MCRT®	Outline Dimensions [mm]														
Model	A	В	C	D ¹	E	F	G	Н	L	M	N	P	K	Q	R
48/9801V	4.75	28.6	38.1	15.9	57.2	139.7	139.7	57.2	215.9	98.0	38.1	88.1	90°	10.3	28.2
48/9802V	4.75	41.3	50.8	19.1	57.2	139.7	139.7	57.2	241.3	104.8	38.1	88.1	90°	10.3	28.2
48/9803V	6.35	43.7	56.4	25.4	66.7	158.8	143.5	63.5	254.0	104.0	38.1	100.8	60°	10.3	48.4
48/9804V	9.53	69.9	91.2	38.1	66.7	158.8	143.5	63.5	323.9	104.0	38.1	100.8	60°	10.3	48.4
48/9806V	15.88	88.9	104.8	63.5	108.0	254.0	222.3	108.0	431.8	142.9	71.4	176.2	60°	Note 2	59.9
48/9807V	19.05	114.3	130.2	76.2	108.0	254.0	222.3	108.0	482.6	149.2	71.4	176.2	60°	Note 2	59.9
48/9808V	25.40	165.1	192.0	114.3	108.0	254.0	215.9	127.0	585.0	159.9	71.4	208.0	60°	Note 2	51.2

^{1.} Tolerance of D diameter is +0.0000/-0.0127 for D <= 63.5" and +0.000/-0.025 for D > 63.5".

^{2.} Slotted 0.531" wide by 1-1/8" long.

^{2.} Slotted 13.5 wide by 28.6 long.

Example of Software Display



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